

# Hypernetwork approach to determination of occupational accident risks

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## Abstract

Economic losses resulting from occupational accidents cause many researchers and policy makers to be interested in this issue. It is important to present effective mathematical methods as well as conventional statistical methods in the analysis of categorical occupational accident data. In this study, a mathematical method about edge estimation on a social network created with hyper-graphs for work accident analysis and prediction is presented. This method treats the process of the random walker evolving on the network with distributed order fractional derivative. The study was carried out numerical calculations in the years 2013–2014 in the dataset occupational accidents occurred in Turkey. The results obtained on a sample give prediction of possible occupational accidents characteristics.

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*Keywords.* hypergraphs, fractional calculus, edge prediction, network analysis.

## 1 Introduction

Occupational accidents that occur globally every year cause economic losses such as injuries, deaths, material and environmental damages. Therefore, the analysis and prediction of occupational accidents are important for both safety managers and policy makers. There are several approaches to the prediction and analysis of occupational accidents, such as traditional statistical analysis [1, 2, 3], questionnaire-based qualitative analysis [4, 5, 6], data-driven machine learning [7, 8, 9], and structured data analysis [10, 11, 12].

Apart from the results of the methods used in the analysis of occupational accidents, the main purpose of this study is to try to predict occupational accidents with the discovery of unforeseen and unexpected new structures. Standard occupational accident approaches all ignore the uncertainty of accidents. Mathematically, uncertainty is studied with fundamental theories such as hypergraph theory, fuzzy set theory, rough set theory, and soft set theory [13, 14, 15, 16]. Such soft computing approaches in occupational accident data have yielded effective results in determining the factors affecting occupational accidents [17].

Many factors affect the occurrence of work accidents. Some of these can be listed as carelessness of human behavior, inexperience at work, insufficient training in safety, unsafe conditions and psychological state of workers. Occupational accident data are vectors that contain descriptive information such as the number of injured people, the environment where the accident occurred, the age of the worker, the marital status of the worker, the level of education, the number of working days of the worker, and the number of days lost as a result of the accident. It is more difficult to deal with categorical variables than with continuous variables. For this reason, graphs are used as a structural data analysis approach in our study.

In mathematics, a combinatorial network representing social relations between a specific group is called a social network. Within an organization of individuals, social network structure encodes the interaction amongst members. Recently, social network approaches have been studied intensively in order to characterize occupational accidents [18, 19, 20, 21, 22]. The idea behind this approach is that workers in the same job sector are affected positively or negatively by other workers. When a sector's social network is established, it is possible to determine the most effective individuals in the communication process in this network with various mathematical and statistical measurements. In this study, we first present a hypergraph formation method for structured occupational accidents data. This method uses parametrization of each category. Then we perform link prediction process on the filtration of simple graph embedding of such hypergraphs. The link prediction model we present is a novel approach and uses fractional evolution of random walker in a network. Fractional calculus is generalization of integer order operations to fractional ones. In fractional derivative a memory function is employed. Then, by using similarity, we determine the possible occupational accidents.

The paper is organized as follows: Section 2 is presented as two parts. In first part, Section 2.1, we present basic of hypergraphs and link prediction. Also, two different graph embeddings of hypergraphs are given. In second part, Section 2.2, we introduce novel link prediction algorithm by considering the fractional evolution of a random walker on a graph. In this section, we give details how the memory function is employed. Moreover, a numerical scheme for solving such link prediction problem is presented. In Section 3, we give detailed computational results on 20132014 Occupational Accidents Data of Turkey. Finally, in Section 4, we present detailed discussion and conclusions.

## 2 Method

### 2.1 Hypernetworks and edge prediction

A natural way to express structural data sets is using graphs composed of vertices and edges. In mathematics, hypergraphs are the generalization of the graph structure in such way that allowing edges contain more than two vertices, and they are explicit data structure to represent hypernetworks. In last decades, hypergraphs and their applications have been studied extensively [23, 24, 25, 26]. In particular, a hypergraph  $H = (V, E)$  is consisting of tuple where  $V$  is set of vertices and  $E$  is set of hyper-edges. Each hyper-edge  $e \in E$  may contain arbitrarily many vertices. Hence,  $e \subset P^V$ . This definition of a hypergraph lead us to conclude that a hypergraph can be considered as a set system. If the elements of  $e \in E$  do not have any order, then we say that  $H$  is an undirected hypergraph. Throughout this study, we only consider undirected hypergraphs. For more detailed definitions and theorems on directed and undirected hypergraphs, we refer readers to [27]. We also need to note that, an undirected simple graph is a special case for a hypergraph in which the size of an edge is restricted to two. Since hypergraphs are the generalization of simple graphs, they encode higher order relations on data sets.

In order to determine hypergraph statistics, we need more definitions such as degrees. The degree distributions are strong indicators on network analysis. Since there is no restriction on a hyperedge cardinality, we can define two type of degrees and their distributions on hypernetworks. In a hypergraph  $H = (V, E)$ ; the degree  $d^V(v)$  of  $v \in V$  is the number of hyper-edges containing  $v$ , whereas the degree  $d^E(e)$  of a hyper-edge  $e \in E$  can be defined as the number of vertices belongs to  $e$ . By counting how many vertices and edges have each degree, we can form the vertex degree

distribution  $P_{d^V(v)}(k)$ , defined by

$$P_{d^V(v)}(k) = \text{fraction of vertices in } H \text{ with the degree } k \quad (2.1)$$

and the hyperedge degree distribution  $P_{d^E(e)}(k)$ , defined by

$$P_{d^E(e)}(k) = \text{fraction of hyperedges in } H \text{ with the degree } k. \quad (2.2)$$

We refer readers to [28] for more details on degree distributions for hypergraphs. For a hypergraph  $H = (V, E)$ , the sequence of vertices and hyper-edges

$$v_1, e_1, v_2, e_2, \dots, v_{k-1}, e_k, v_k$$

is called a hyper-walk between the vertices  $v_1, v_k \in V$  for  $1 \leq i \leq k - 1$ .

In a hypergraph setting, there are several hyper-edge prediction measures used in literature. Let  $N(v)$  denote the set of neighbours of  $v \in V$  in  $H(V, E)$ . If  $C$  is all the set of absent hyper-edges in  $H$ , then we use the following features for each possible hyper-edge candidate for  $c \in C$  with the score function  $x$  as

1. Common Neighbours (CN) [29]:  $x(c) = \bigcap_{v_i \subseteq c} N(v_i)$

2. Jaccard Coefficient (JC) [30]:  $x(c) = \frac{\bigcap_{v_i \subseteq c} N(v_i)}{\bigcup_{v_i \subseteq c} N(v_i)}$

3. Adamic-Adar Index (AA) [31]:  $x(c) = \sum_{v_j \in \bigcap_{v_i \subseteq c} N(v_i)} \frac{1}{\log |N(v_j)|}$

4. Katz Index (KI) [29]:  $\sum_{k=1}^{\infty} \beta^k |\mathcal{L}_{ij}^{<k>}|$ , where  $\mathcal{L}_{ij}^{<k>}$  is the set of all hyper-walks, with length  $k$  connecting  $v_i$  and  $v_j$ , and  $\beta$  is a free parameter.

With the expansion of the usage disciplines of simple graph theory, many algorithms are defined on these structures. Although hypergraphs contain higher order information that simple graphs cannot encode, it can be said that technical and methodological developments on hypergraph theory are not as remarkable as simple graph theory. There are several methods for embedding high-order relationship information contained in hypergraphs into simple graphs. The most common embedding method is to bipartite graphs which are subclasses of simple graphs such that the set of vertices decomposed into two disjoint sets in a way that none of two vertices are within the same set are adjacent [27]. For a hypergraph  $H = (V, E)$ , its bipartite graph representation  $G_B = (V_1 \cup V_2, E_B)$  is tuple with  $V_1 = V$ ,  $V_2 = E$ , and  $E_B$  is the set of dyadic relations of hyper-edge inclusions. The second embedding method we mention in this study is related to the connectivity of the vertices through hyper-edges. Let  $H = (V, E)$  be a hypergraph. Since each  $e_i \in E$  involves arbitrarily many vertices, there exist such a simple graph  $G_{C_i} = (e_i, E_{C_i})$  such that each vertices in  $e_i$  are adjacent. Therefore, the Boolean sum of  $G_C = G_{C_1} \oplus \dots \oplus G_{C_m}$  emerges as a simple graph representation of  $H$  regarding to hyper-connectivity of vertices [32].

In Figure 1, we present an example for a hypergraph and its simple graph representations. In this example, the hypergraph  $H = (V, E)$  is given with edge sets as  $e_1 = \{v_1, v_2, v_5, v_6\}$ ,  $e_2 = \{v_6, v_8, v_9\}$ ,  $e_3 = \{v_2, v_3, v_4\}$ , and  $e_4 = \{v_7, v_{10}\}$ , where  $V = \{v_1, v_2, \dots, v_{10}\}$ . The bipartite embedding of  $H$  is a simple graph  $G_B$  with the vertex set  $V_B = V \cup E$  and the elements of  $E_B$  are formed by inclusion. Moreover, the embedding of  $H$  regarding to hyper-connectivity of vertices is a simple graph  $G_C = G_{C_1} \oplus \dots \oplus G_{C_4}$ .

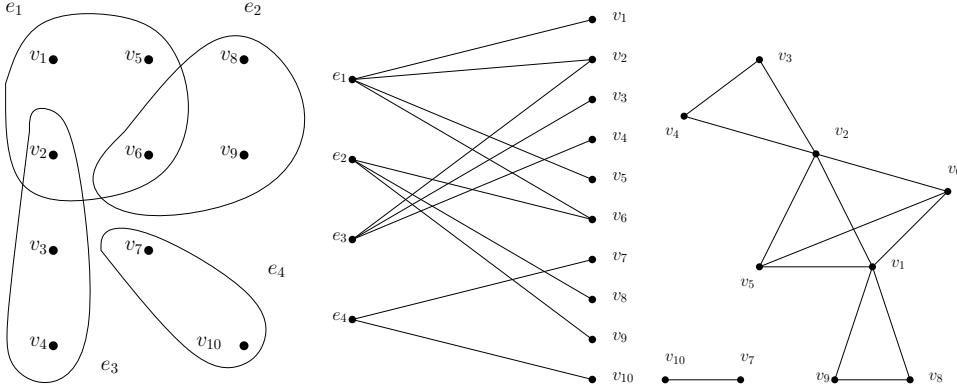


FIGURE 1. Hypergraph  $H = (V, E)$  is on the left, the simple graph  $G_B = (V_B, E_B)$  in in the middle, and the simple graph  $G_C = (V, E_C)$  is on the right

While performing edge prediction task on  $H = (V, E)$ , the indices  $CN$ ,  $JC$ ,  $AA$ , and  $KI$  give the score of the hyper-edge tendency to be included in  $E$ . In order to keep bipartite topology of  $G_B$  embedding of  $H$ , such task should be performed as edges included in between  $e_i$  and  $v_j$ . Otherwise, the topology of  $H$  will change by emerging multi-hyperedges or loops in vertices. The motivation behind the  $G_C$  embedding of  $H$  is representing the hypergraph structure as a clique-complex. Hence, as the predicted hyper-edges being included in  $E$ , the updated embedding will still remain as a clique complex. However, such complexes are not regular. Therefore, the hyper-edge prediction on  $H$  becomes clique prediction process on  $G_C$ .

## 2.2 Communicability centrality with distributed power-law memory

In network analysis, centrality of a vertex is and indicator which measure importance of a vertex in a network [33, 34, 35]. There are several centrality measures in literature that are used for different purposes. In a network, an important quantity for determining communication centrality of a vertex is the communicability function [36, 37], defined by for vertices  $i$  and  $j$  as

$$Comm_{ij} = \sum_{k=0}^{\infty} \frac{A_{ij}^k}{k!} = \exp(A)_{ij} = \sum_{\mu=1}^{|V|} \exp(\lambda_{\mu}) \varphi_{\mu}(i) \varphi_{\mu}(j), \quad (2.3)$$

where  $A$  is the adjacency matrix of the network represented by  $G = (V, E)$  and right-hand side emerges from the spectral decomposition of each term of the Taylor expansion of  $A_{ij}^k$ .

The communicability function defined in 2.3 can be visualized in different way. Now, let us consider a random-walker distribution on  $G$  described with  $\vec{\varphi}(t)$ , where  $t$  is the variable of time.

Then, the matrix differential equation

$$\frac{d\vec{\varphi}(t)}{dt} = A\vec{\varphi}(t) \quad (2.4)$$

gives the time evaluation of the random-walker  $\vec{\varphi}(t)$ . The analytical solution of the Equation 2.4 is  $\vec{\varphi}(t) = \exp(At)\vec{\varphi}(0)$ . Hence,  $\exp(A)$  is the time evolution operator.

In a social network, the evaluation of a random walker can be affected from regulations done by institutions. Hence, we need to include memory of a random-walker evaluating on  $G$ . Now, let us assume that the endogenous variable  $Y(t)$  is dependent on the history of the change of  $\vec{\varphi}(\tau)$  in  $G$  for  $\tau \in [0, t]$ . Then, the endogenous variable can be defined by

$$Y(t) = \int_0^t M(t, \tau)\vec{\varphi}(\tau)d\tau, \quad (2.5)$$

where  $M(t, \tau)$  is the kernel of the Volterra type operator and called the memory function. Furthermore, if we assume homogeneity in time, then

$$\frac{\partial M(t, \tau)}{\partial t} + \frac{\partial M(t, \tau)}{\partial \tau} = 0. \quad (2.6)$$

The solution of the Equation 2.6 is  $M(t, \tau) = M(t - \tau)$ .

In this study, we assume that the evaluation of the random-walker has power-law fading memory; that is,

$$M(t, \tau) = \frac{1}{\Gamma(n - \alpha)} \frac{m}{(t - \tau)^{\alpha - n + 1}}, \quad (2.7)$$

where  $\alpha > 0$  is the power-law fading parameter,  $m(\alpha) \in \mathbb{R}$ ,  $n = \llbracket \alpha \rrbracket + 1$ , and  $\Gamma$  is the Gamma-function.

If we substitute memory function given in Equation 2.7 into the Equation 2.5, then the endogenous variable  $Y(t)$  becomes

$$Y(t) = m (D_{0+}^{\alpha} \vec{\varphi}(t)) \quad (2.8)$$

with

$$D_{0+}^{\alpha} \vec{\varphi}(t) = \frac{1}{\Gamma(n - \alpha)} \int_0^t \frac{\vec{\varphi}^{(n)}(\tau)d\tau}{(t - \tau)^{\alpha - n + 1}}, \quad (2.9)$$

where  $\vec{\varphi}^{(n)}(\tau) = \frac{\partial^n \vec{\varphi}}{\partial \tau^n}$ . The Equation 2.9 is called left-sided Caputo fractional derivative of  $\vec{\varphi}(t)$ .

The memory function we employ into the evaluation process of a random-walker makes the walker remember recent historical changes. However, such memory can not be the same for each step of the evaluation in social systems. Hence, if we distribute  $\alpha$  parameter on time interval, with the cumulative distribution function  $p(\alpha)$  let us to have the memory function as

$$M(t - \tau) = \int_0^1 \frac{p(\alpha)(t - \tau)^{n - \alpha - 1}}{\Gamma(\alpha - n)} d\alpha. \quad (2.10)$$

Then, it is possible to define Caputo fractional derivative of distributed order on  $[0, 1]$  as

$$D_{0+}^{[0,1]} \vec{\varphi}(t) = \int_0^1 p(\alpha) D_{0+}^{\alpha} \vec{\varphi}(t) d\alpha, \quad (2.11)$$

where  $\int_0^1 p(\alpha) d\alpha = 0$ . Therefore, the evaluation of the random-walker with distributed order power-law memory emerges as

$$D_{0+}^{[0,1]} \vec{\varphi}(t) = A \vec{\varphi}(t). \quad (2.12)$$

The solution of the Equation 2.12 yields us to obtain random-walker distribution on  $G$  with adjacency matrix  $A$ . Then, it is possible to determine communicability centrality with distributed power-law memory of a particular vertex. Since the solution of the Equation 2.12 directly varies respect to the definition of  $p(\alpha)$ , we present a fast discretization scheme for the numerical solution. The numerical solution respect to finite differences of distributed order fractional differential equations are intensively studied in [38, 39, 40, 41, 42].

The communicability centrality with distributed power-law memory of a particular vertex depends on the  $ij$ -th entity of the vector  $\vec{\varphi}(t)$ . Since the matrix  $A$  encodes the neighborhood data on  $G$ , the  $ij$ -th of the vector  $\vec{\varphi}(t)$  satisfies

$$D_{0+}^{[0,1]} \vec{\varphi}_{ij}(t) = A_{ij} \vec{\varphi}_{ij}(t). \quad (2.13)$$

Now, let us obtain the numerical solution of the distributed order equation 2.13. In order to obtain discretization scheme, we discretize the interval  $[0, 1]$ , in which the order  $\alpha$  is changing and  $\Delta\alpha_k$  are the grid steps. We shall note that such discretization does not need to be equidistant; however, in this study, we give the discretization scheme respect to equidistant grid steps. Then we have

$$\begin{aligned} D_{0+}^{[0,1]} \vec{\varphi}_{ij}(t) &= p(\alpha) D_{0+}^{\alpha} \vec{\varphi}_{ij}(t) d\alpha \\ &\approx \sum_{k=1}^n p(\alpha_k) (D_{0+}^{\alpha_k} \vec{\varphi}_{ij}(t)) \Delta\alpha_k. \end{aligned} \quad (2.14)$$

In [43], approximation to the right-sided Caputo derivatives are given with a matrix

$$F_n^{\alpha} = \frac{1}{\tau^{\alpha}} \begin{pmatrix} \omega_0^{\alpha} & 0 & 0 & 0 & \dots & 0 \\ \omega_1^{\alpha} & \omega_0^{\alpha} & 0 & 0 & \dots & 0 \\ \omega_2^{\alpha} & \omega_1^{\alpha} & \omega_0^{\alpha} & 0 & \dots & 0 \\ \ddots & \ddots & \ddots & \ddots & \vdots & \vdots \\ \omega_{n-1}^{\alpha} & \ddots & \omega_2^{\alpha} & \omega_1^{\alpha} & \omega_0^{\alpha} & 0 \\ \omega_n^{\alpha} & \omega_{n-1}^{\alpha} & \ddots & \omega_2^{\alpha} & \omega_1^{\alpha} & \omega_0^{\alpha} \end{pmatrix}, \quad (2.15)$$

where  $t = j\tau$ ,  $j = 0, 1, \dots, n$ , and

$$\omega_j^{\alpha} = (-1)^j \binom{\alpha}{j}.$$

By employing the matrix given in Equation 2.15 and the approximation given in Equation 2.14, we can have the discretized scheme for the Equation 2.13 as

$$\sum_{k=1}^n p(\alpha_k) F_n^{\alpha} \Delta\alpha_k = A_{ij} \vec{\varphi}_{ij}. \quad (2.16)$$

Then, the solution of Equation 2.16 is  $n \times n$ -matrix

$$\hat{\varphi} = \sum_{k=1}^n p(\alpha_k) \Delta \alpha_k A^* F_n^\alpha, \quad (2.17)$$

where  $A^*$  is Moore-Penrose matrix of the adjacency matrix.

### 3 Results on occupational accident data of Turkey

#### 3.1 Data and network construction

In this study, the raw data of occupational accidents occurred in Turkey in 2013–2014 are used. Turkish Social Security Agency (SGK) has permitted to be shared the raw data with an official permission of number 99604924/910/4422955 and date 27/08/2015. The entries containing missing information were cleared from the raw data and then 432090 pieces of data were obtained. The sample data set is randomly chosen to be 10000 to perform analyses. In the selection of the sample data set, 18 sectors with the highest number of occupational accidents were selected. The selected sectors are expressed in 4-digit *NACE* codes in this study. The web-site "<https://opendata.eulerhermes.com>" is referred to the readers for relevant explanations of the sectors and *NACE* codes.

The entries of occupational accident information are taken as Number of Working Days, Age, Gender, Marital Status, Loss of Work Days, Vocational Education, Occupational Safety Training, Education Status, Number of Persons in Accident. In [44], authors briefly introduced a network formation method for similar data set by using similarity of each data entry. Their method also includes the information about the place of the occupational accident. In this study, we follow a novel way to determine hypernetwork structure. First, data sets for each *NACE* code are divided into subgroups. Different parameters used when dividing into subgroups are given in Table 1.

<b>Number of Working Days</b> ( $t \equiv$ days)					
$0 \leq t < 400$	$400 \leq t < 1000$	$1000 \leq t < 2000$	$2000 \leq t < 3000$	$3000 \leq t < 4000$	$t \geq 400$
<b>Age</b> ( $t \equiv$ years)					
$18 \leq t < 25$	$25 \leq t < 30$	$30 \leq t < 35$	$35 \leq t < 40$	$40 \leq t < 45$	$t \geq 45$
<b>Working Days Loss</b> ( $t \equiv$ days)					
$0 \leq t \leq 1$	$1 < t \leq 3$	$3 \leq t < 5$	$5 \leq t < 8$	$8 \leq t < 10$	$t \geq 10$
<b>Number of Persons in the Accident</b>					
1		1-3		>3	
<b>Educational Status</b>					
Elementary School		Secondary School		High School / University / Graduate	
<b>Gender</b>					
Male			Female		
<b>Martial Status</b>					
Married		Bachelor / Bachelorette		Other	
<b>Vocational Training</b>					
Yes			No		
<b>Occupational Safety Education</b>					
Yes			No		

TABLE 1. The parameters list for network formation

The hypernetwork representation of each *NACE* sector data is composed of hyper-edges which are parameters for sub-grouping, and occupational accidents as vertex set. Then, a weighted simple-graph representation  $G_C$  is used for link prediction procedure.

### 3.2 Computational results

In this section, we first present the results of hypernetworks of each *NACE* sector data. Hyper-edge distributions are presented in Figure 2 and vertex degree distributions of respect  $G_B$ . are presented in Figure 3.

From the distributions of  $H$  and  $G_B$ , it is straightforward that the  $G_C$  representations of  $H$  of each *NACE* sector which encode the connectivity of agents in complex environment emerge as complete graphs. Complete graphs are combinatorial objects in which every pair of distinct vertices is connected by a unique edge. Hence, link prediction on  $G_C$  will be a null operation. However, this property assure us about the hypothesis of this study which depends on the information flow amongst agents in context of occupational accidents. In order to perform link prediction, we need to filter each  $G_C$  by using very known method called minimum spanning trees. A minimum spanning tree (*MST*) filtration of  $G_C$  is a subgraph that connects all the vertices together, without any cycles and with the minimum possible total edge weight. In this study, for the weighting scheme, we follow the cosine similarity within each *NACE* sector data set. Then, the link prediction process is applied to *MST* structure. The higher similarity scores on *MST* measures the highest possibility of occupational accident to appear.

In order to explain this filtration process, let us consider “Repair of electrical equipment” sector with *NACE* code 3314. The sample size of this data set is 156. Its distance matrix based on cosine similarity and *MST* filtration which can be considered as hierarchical clustering are given in Figure 4.

In order to perform link prediction on *MST* filtrations of  $G_C$  graphs, we use novel similarity measure communicability centrality with distributed power-law fading as explained in Section 2.2. The solution method described in Equation 2.17 has discretized scheme with  $n$ -steps. Since  $A_{ij}$  denotes the adjacency matrix of *MST*, we consider  $n$  to be equal to size of the vertex set of *MST*. Moreover, the adjacency matrices of *MSTs* are sparse. Therefore, in order to guarantee the numerical solution of Equation 2.13, we use Moore-Penrose inverse of  $A_{ij}$ . Besides, as the random walker decisions affected by the institutional regulations, the distribution of those regulations amongst agent are considered in two ways, namely normal and logistic distributions. In normal distribution case, the random walker’s power-law fading memory is distributed without making strong assumptions. However, in later case which is logistic distribution, the power-law fading memory of random walker is distributed respect to that agents have also a learning process. In this present study, we perform our analyses minimally affected by the diffusion process, that is we only consider the fractional order differentiation to be  $\alpha = 0.5$ . In Figures 5–24, we present the numerical solution of Equation 2.13 for each *NACE* sectors, with different distributions and  $\alpha = 0.5$ .



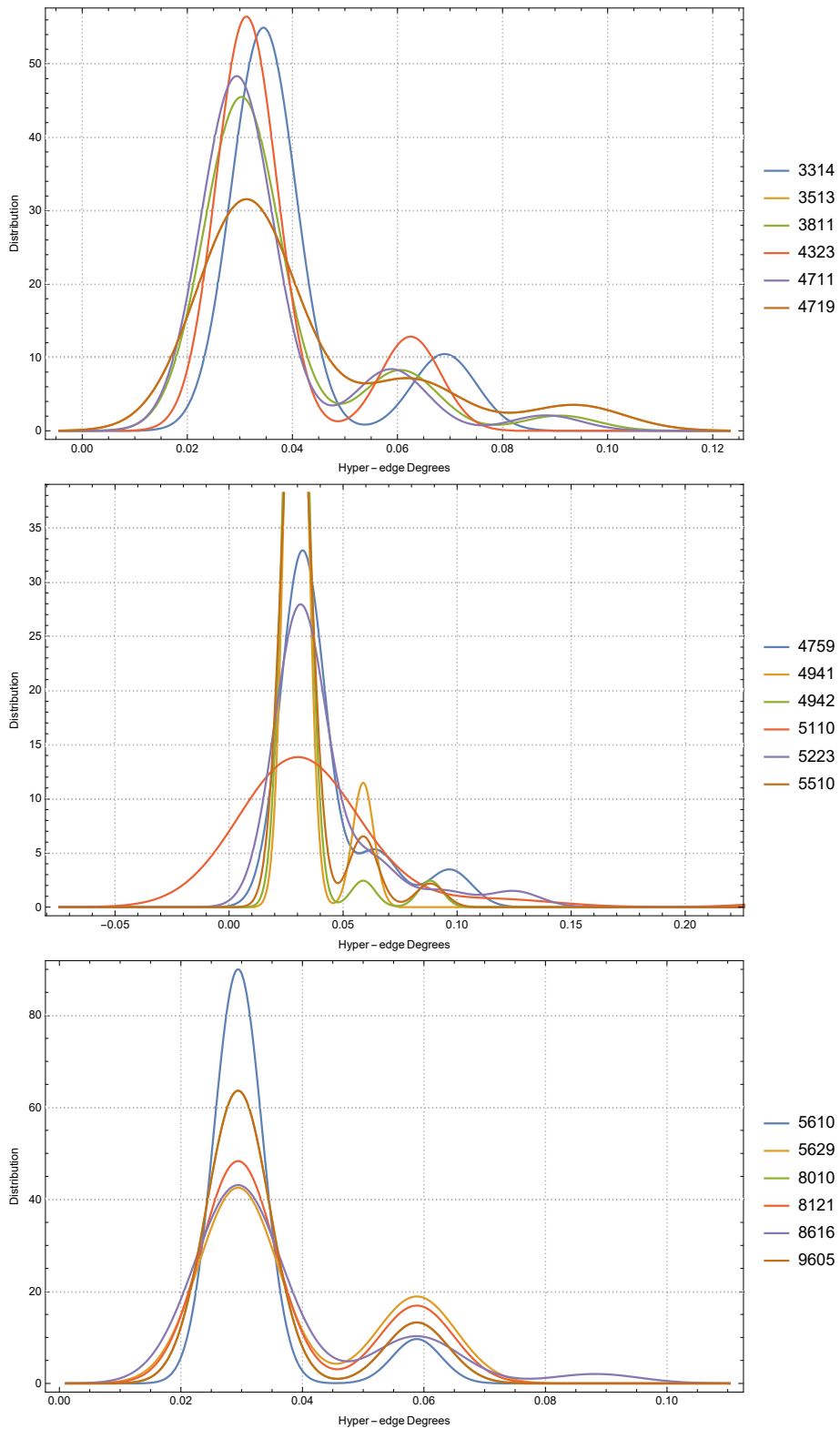


FIGURE 2. Hyper-edge degree distributions of each *NACE* sector.

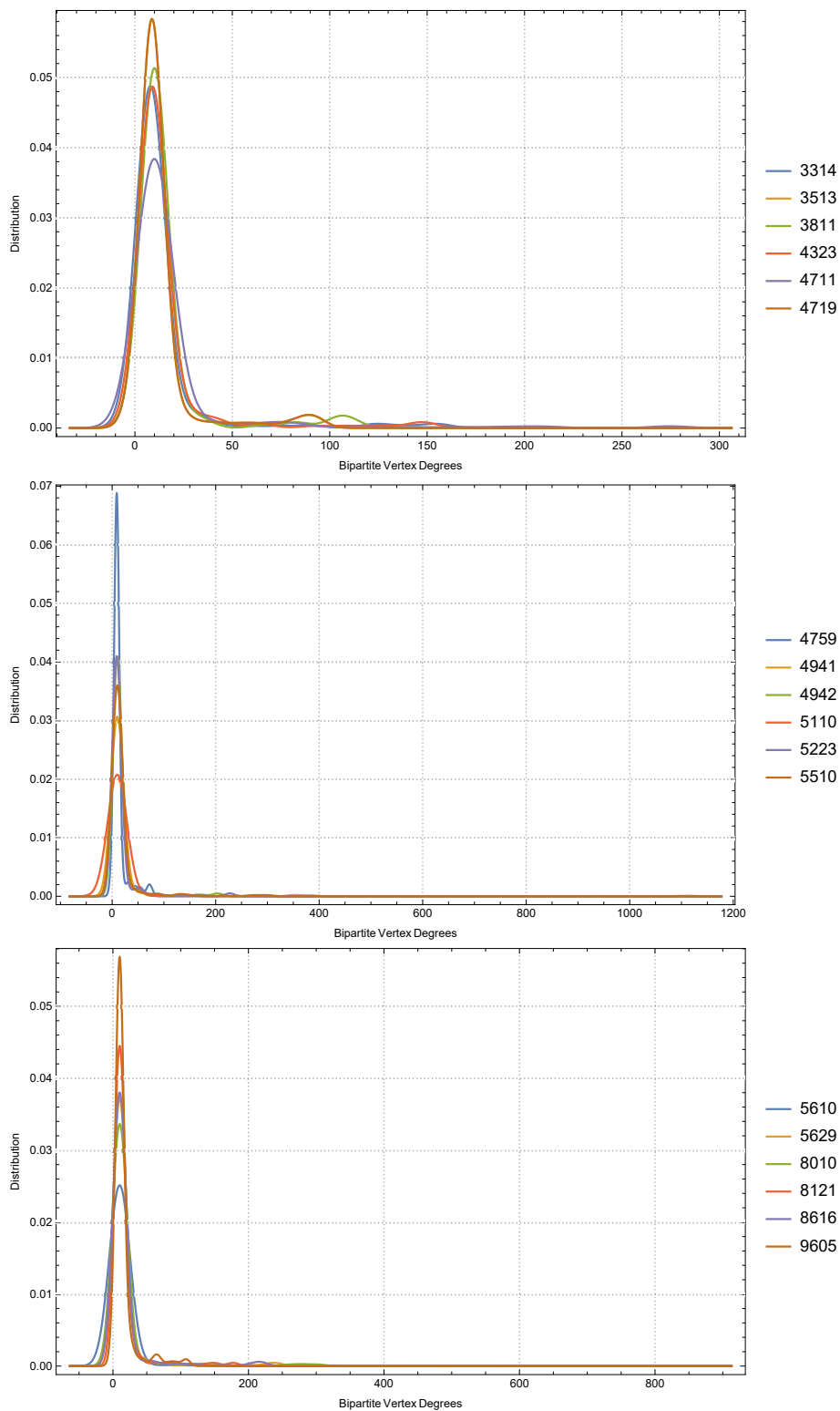


FIGURE 3. Vertex degree distributions of bipartite graphs  $G_B$  of each *NACE* sector.

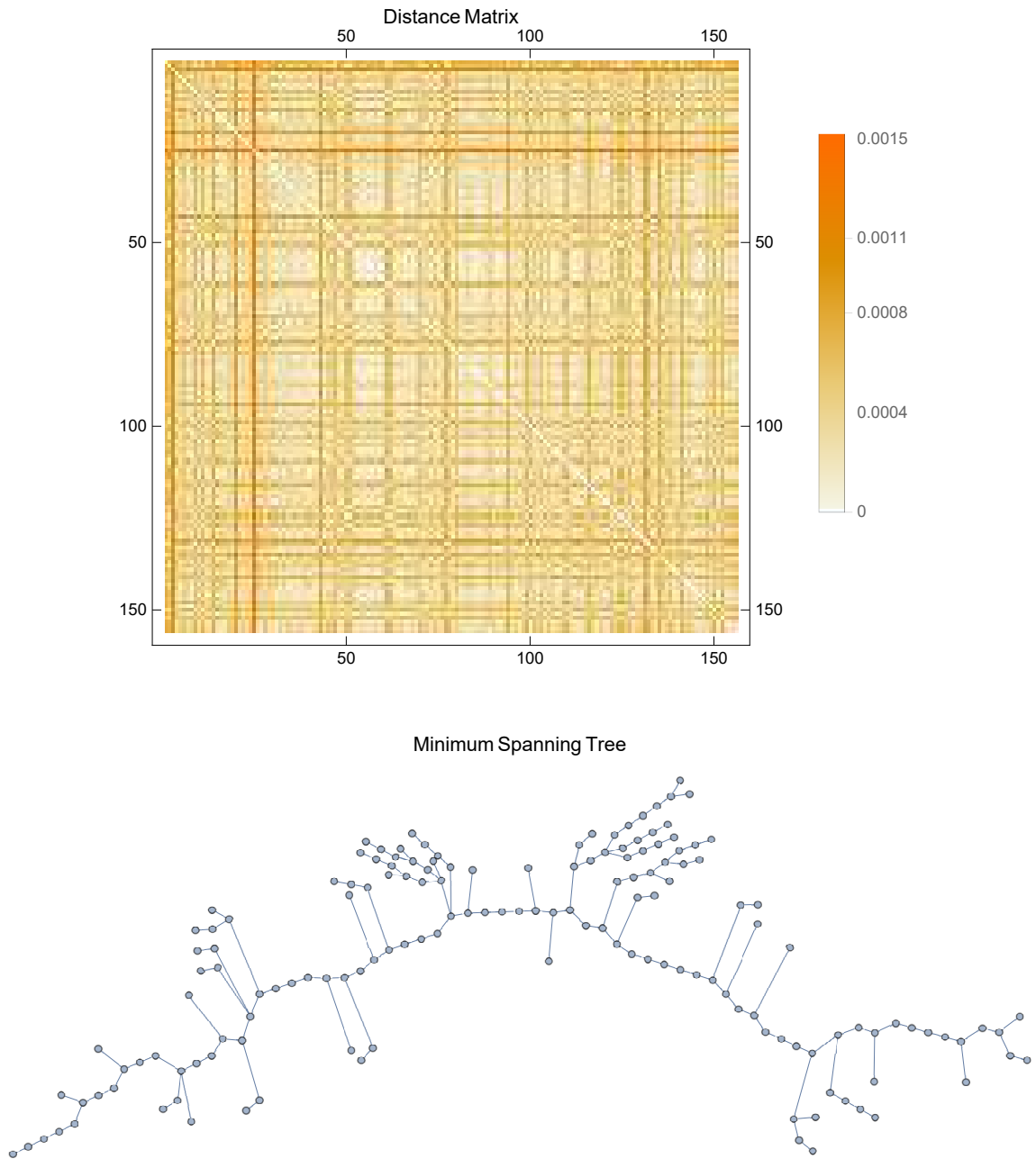


FIGURE 4. Filtration of  $G_C$  representation of 3314

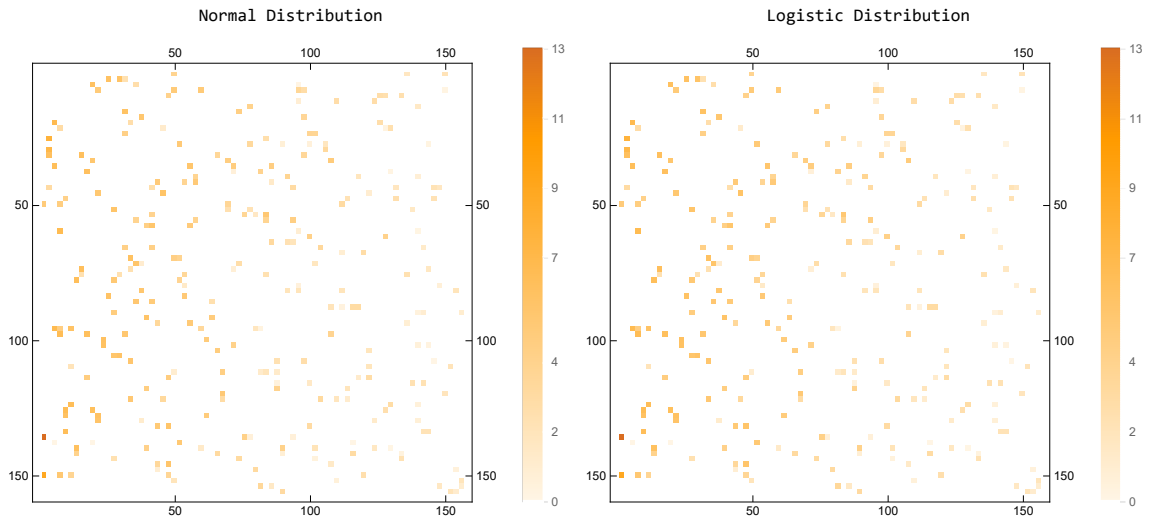


FIGURE 5. Distributed order communicability matrix of *NACE* sector 3314 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

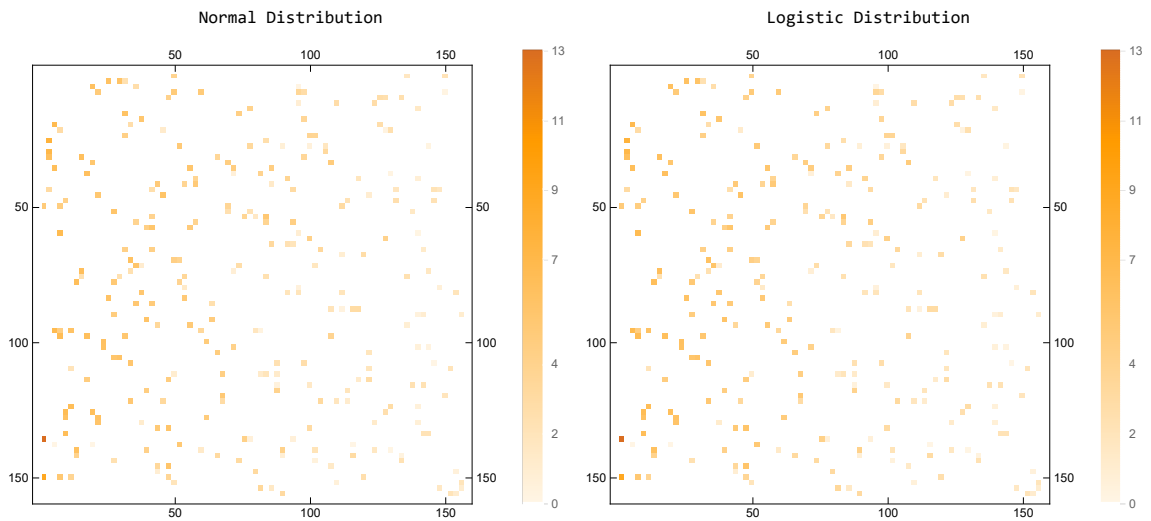


FIGURE 6. Distributed order communicability matrix of *NACE* sector 3513 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

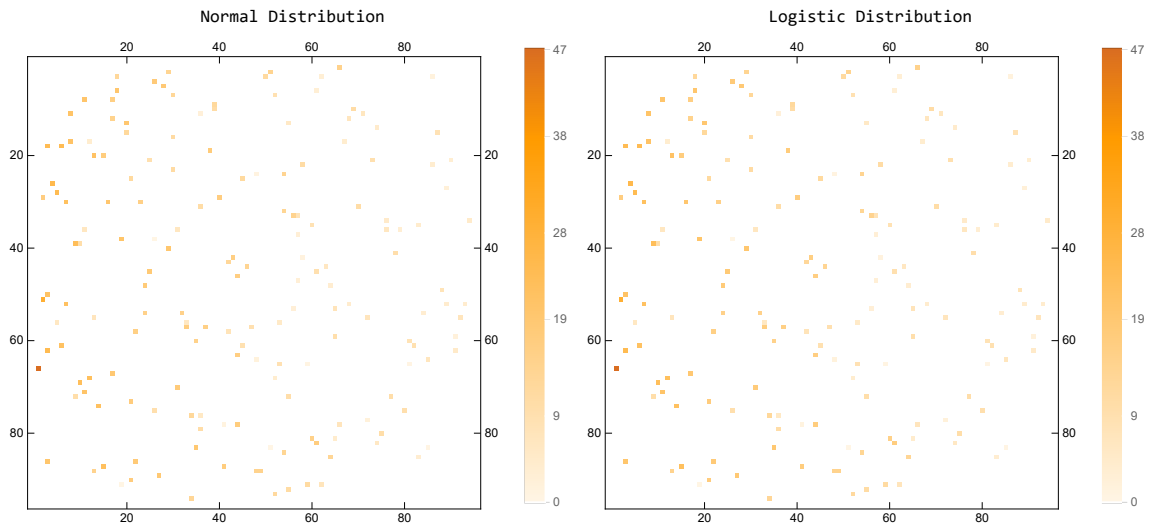


FIGURE 7. Distributed order communicability matrix of *NACE* sector 3811 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

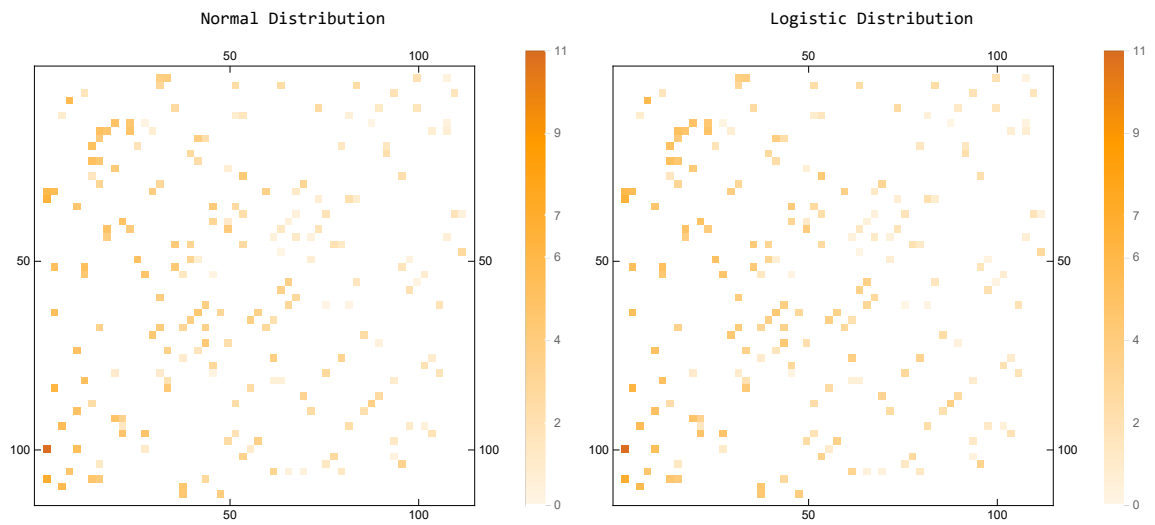


FIGURE 8. Distributed order communicability matrix of *NACE* sector 4323 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

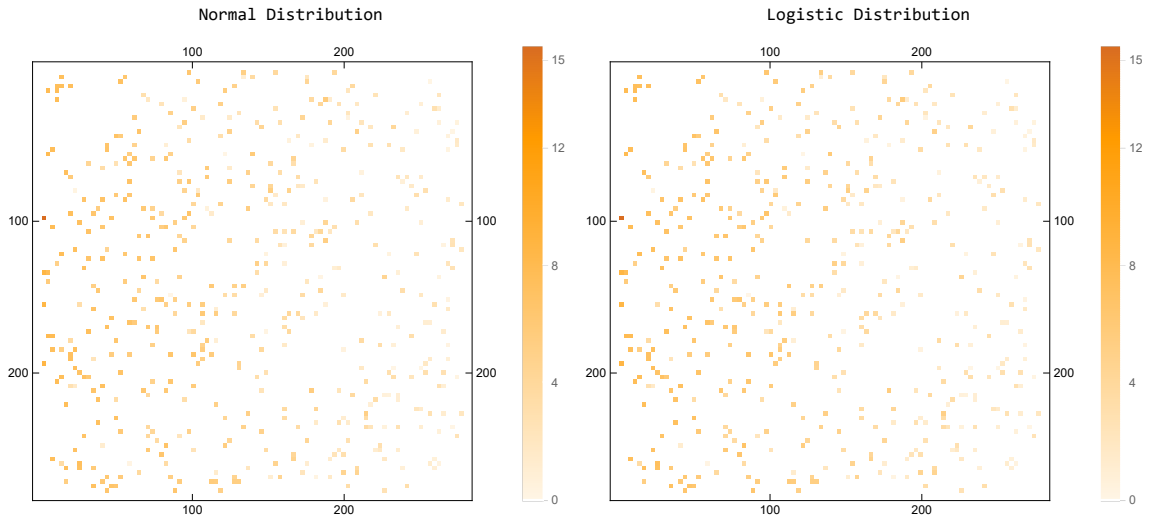


FIGURE 9. Distributed order communicability matrix of *NACE* sector 4711 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

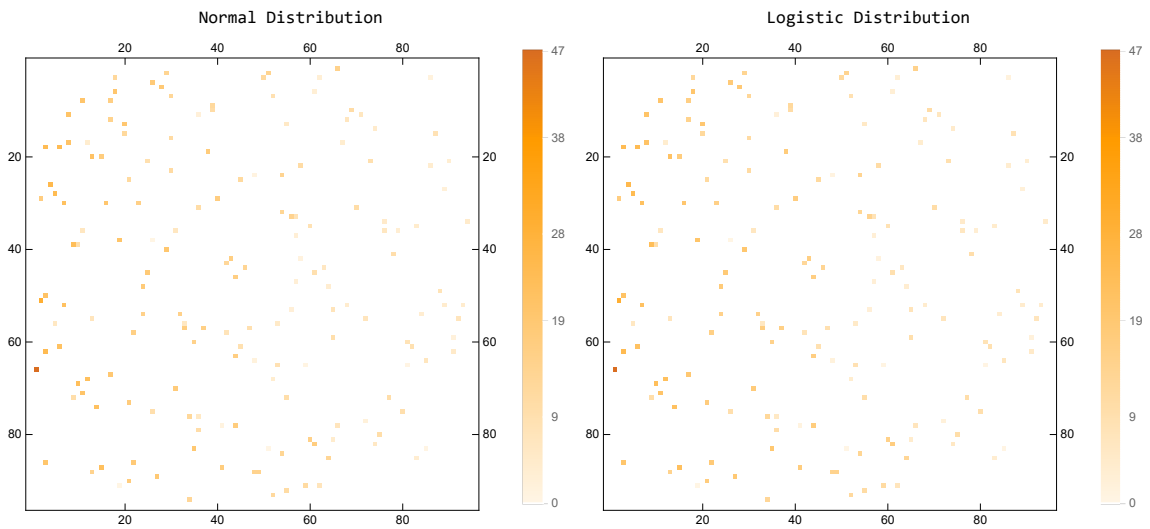


FIGURE 10. Distributed order communicability matrix of *NACE* sector 4719 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

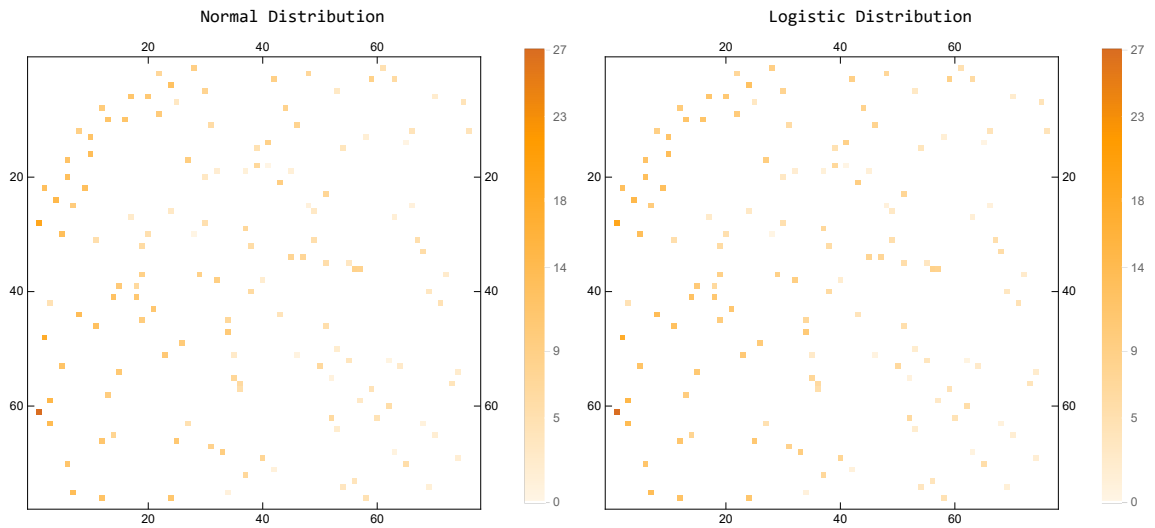


FIGURE 11. Distributed order communicability matrix of *NACE* sector 4759 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

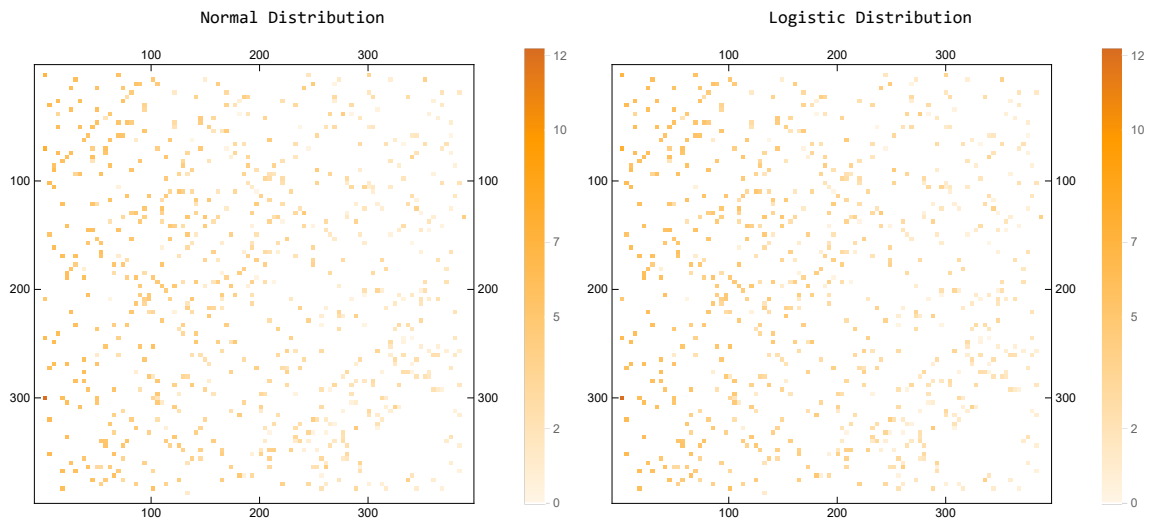


FIGURE 12. Distributed order communicability matrix of *NACE* sector 4941 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

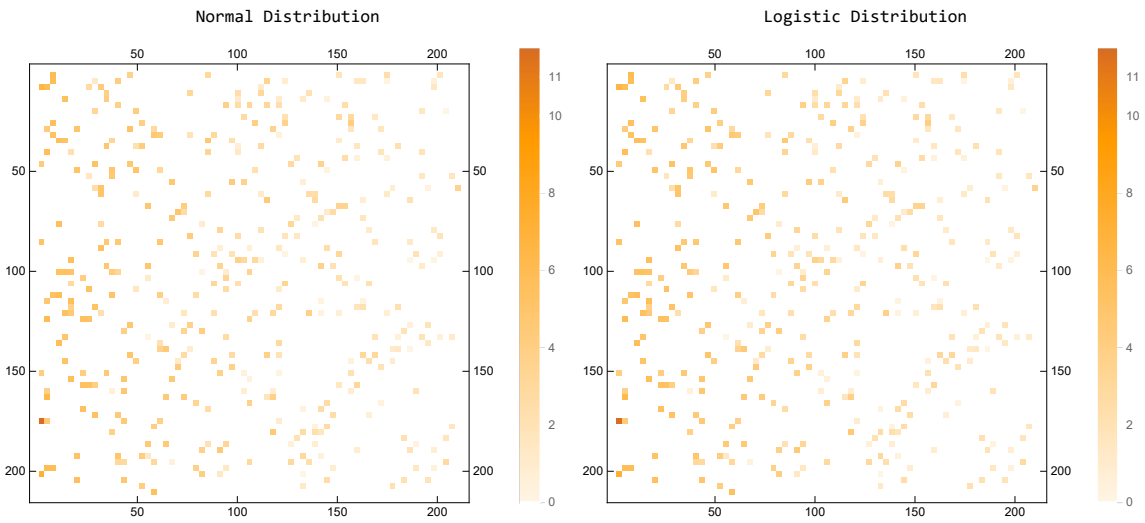


FIGURE 13. Distributed order communicability matrix of *NACE* sector 4942 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

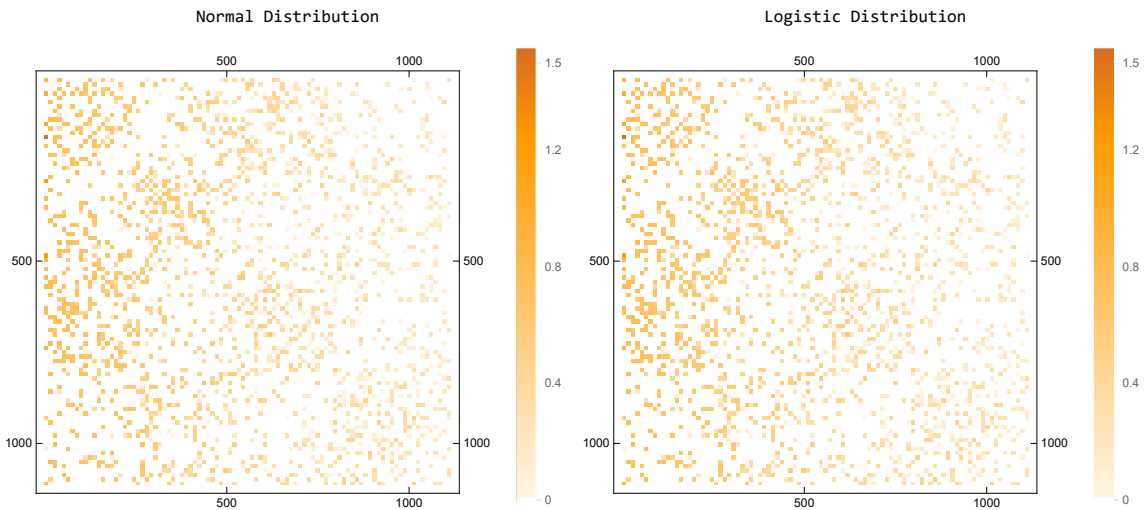


FIGURE 14. Distributed order communicability matrix of *NACE* sector 5110 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$



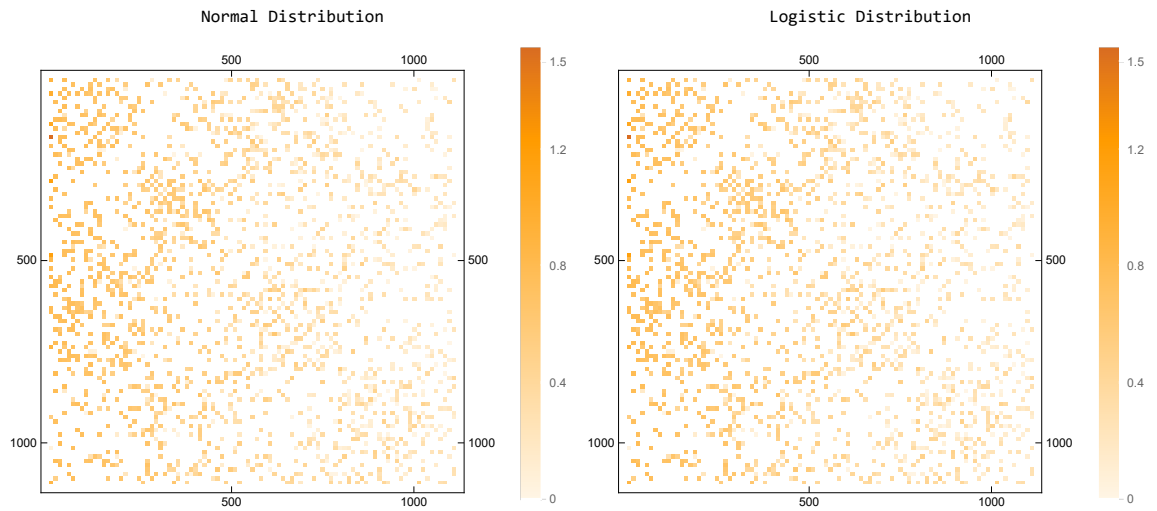


FIGURE 15. Distributed order communicability matrix of *NACE* sector 5223 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

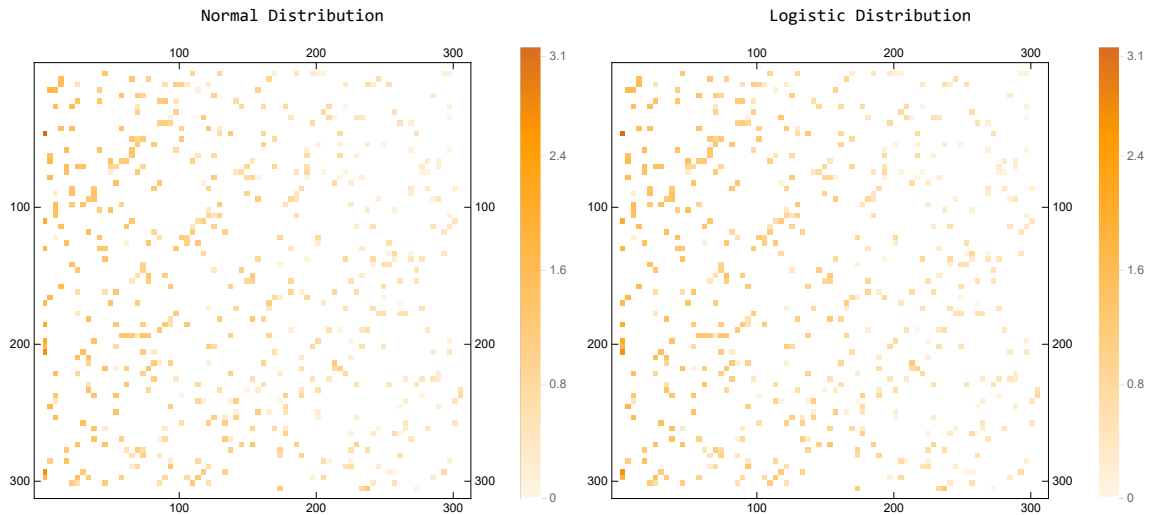


FIGURE 16. Distributed order communicability matrix of *NACE* sector 5510 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

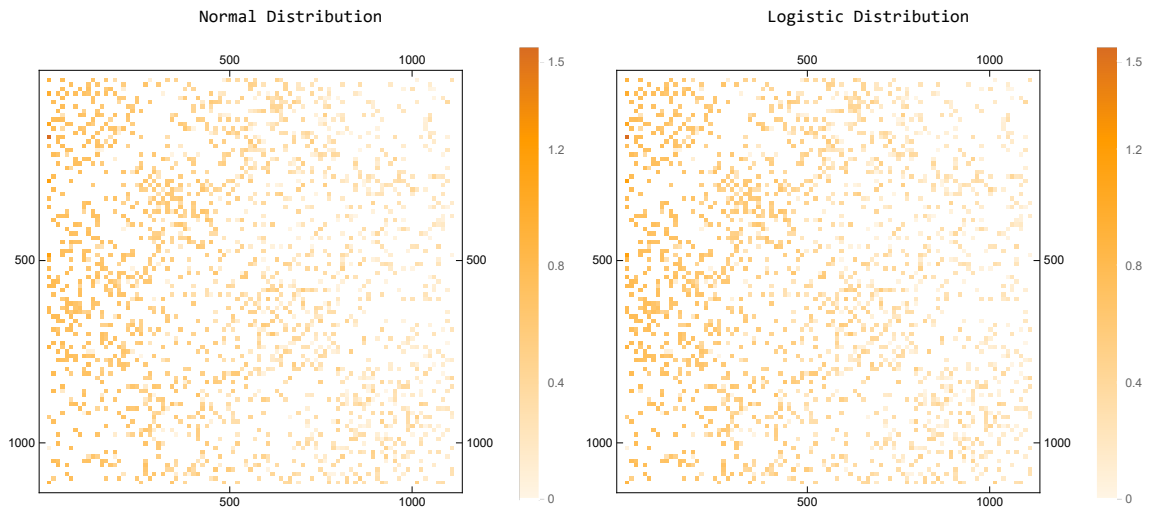


FIGURE 17. Distributed order communicability matrix of *NACE* sector 5223 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

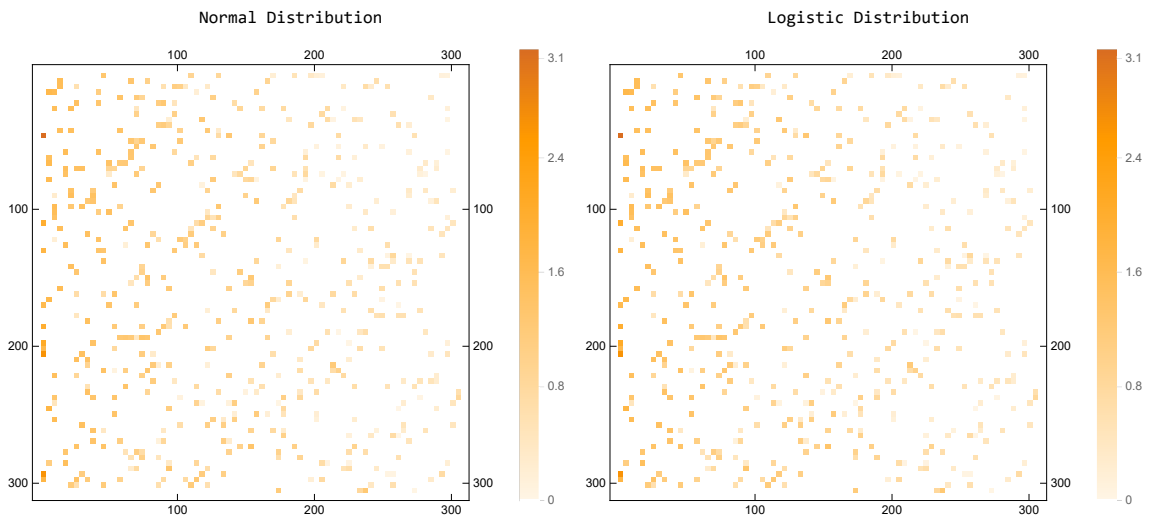


FIGURE 18. Distributed order communicability matrix of *NACE* sector 5510 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

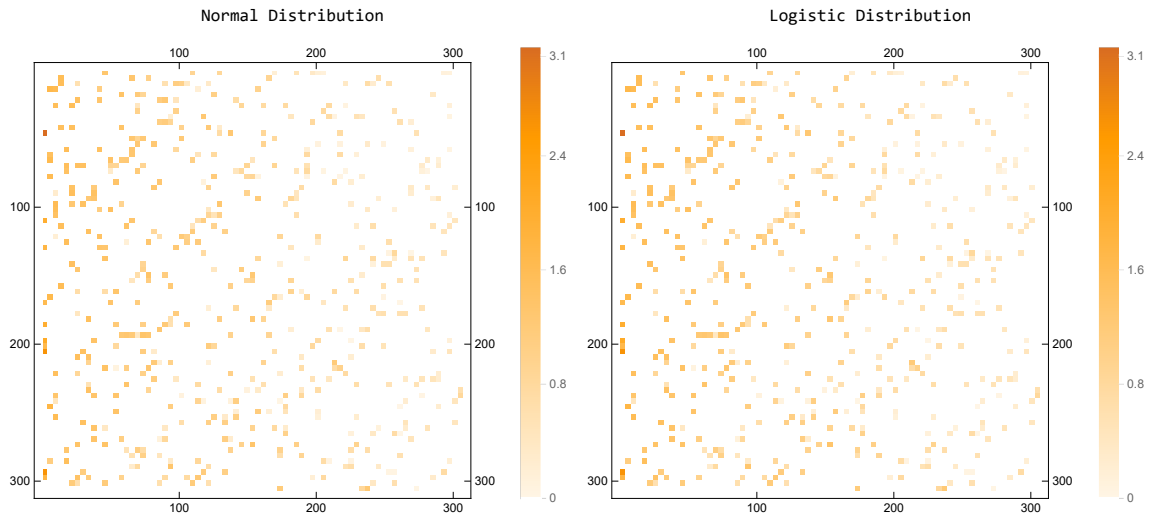


FIGURE 19. Distributed order communicability matrix of *NACE* sector 5610 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

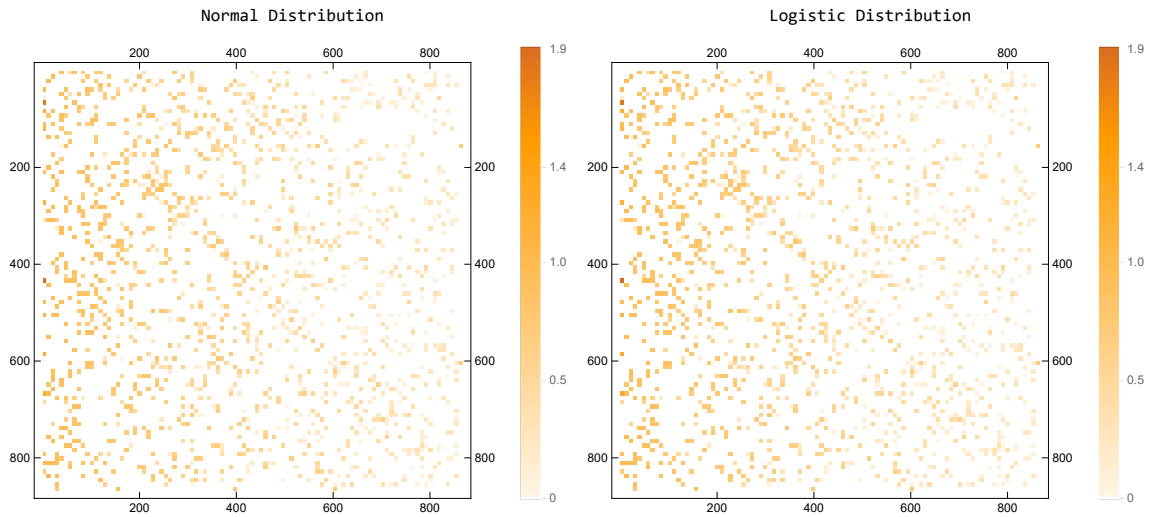


FIGURE 20. Distributed order communicability matrix of *NACE* sector 5629 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

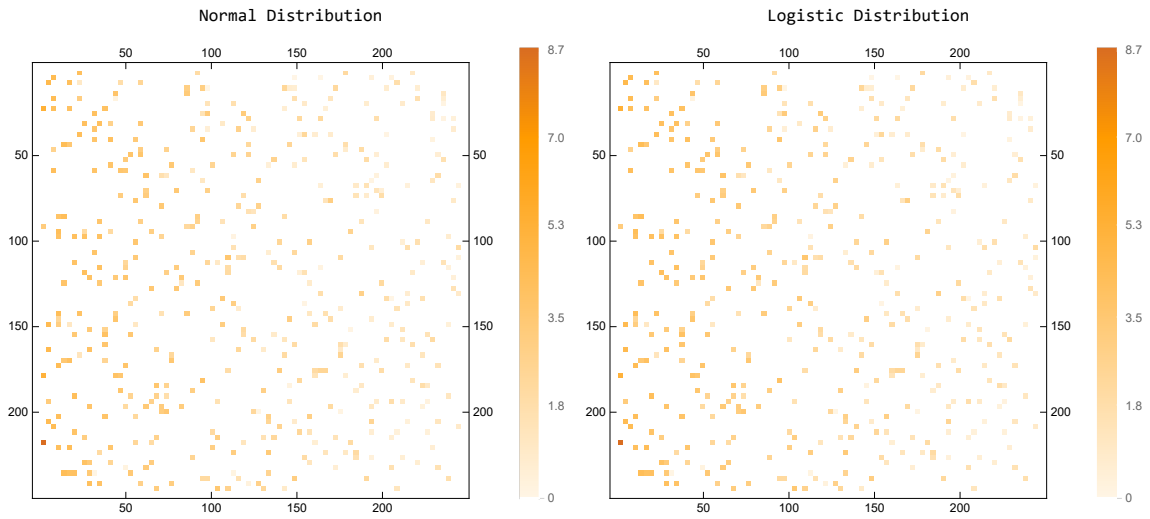


FIGURE 21. Distributed order communicability matrix of *NACE* sector 8010 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

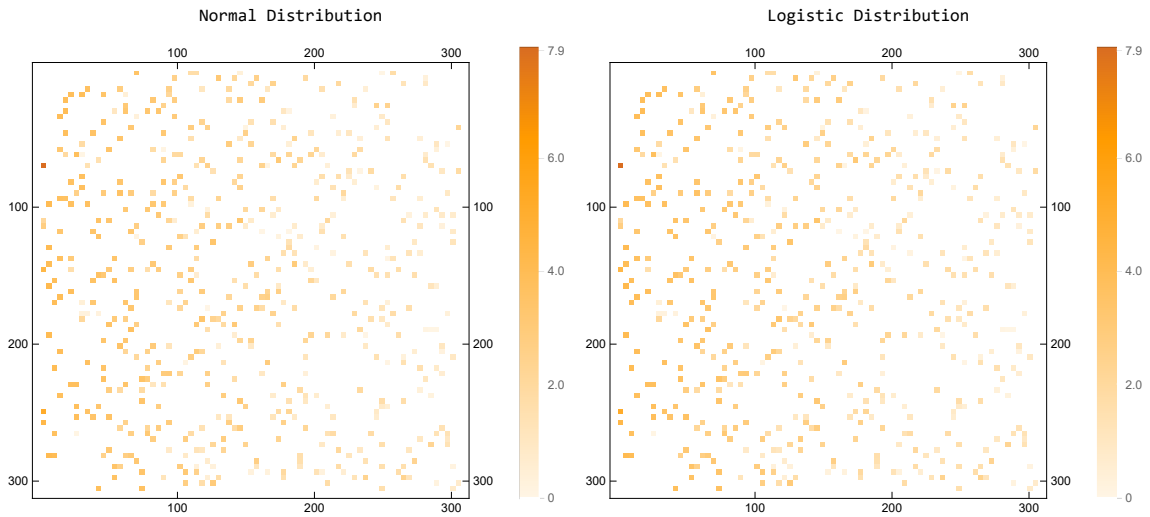


FIGURE 22. Distributed order communicability matrix of *NACE* sector 8121 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

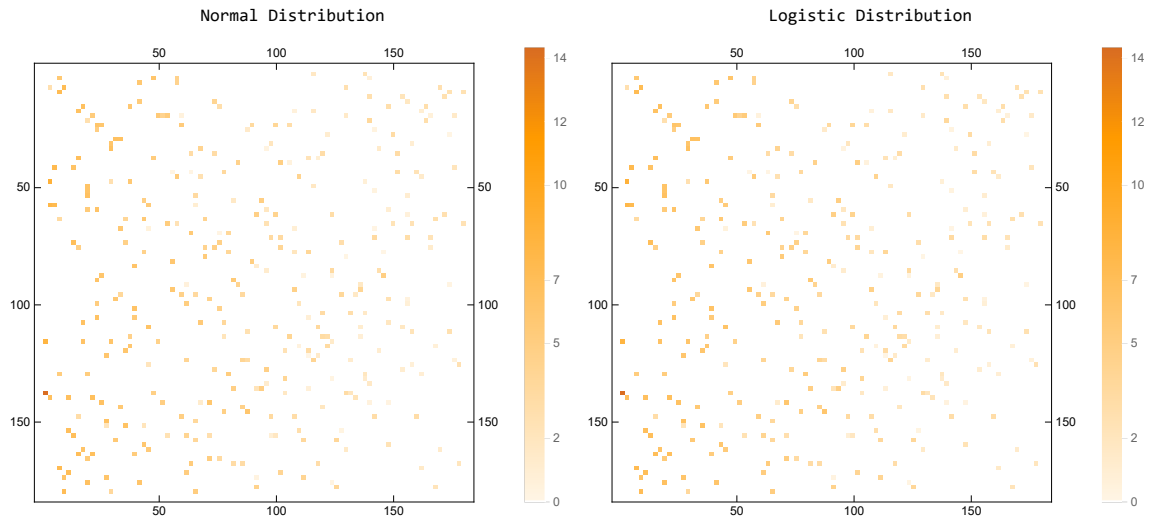


FIGURE 23. Distributed order communicability matrix of *NACE* sector 8616 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

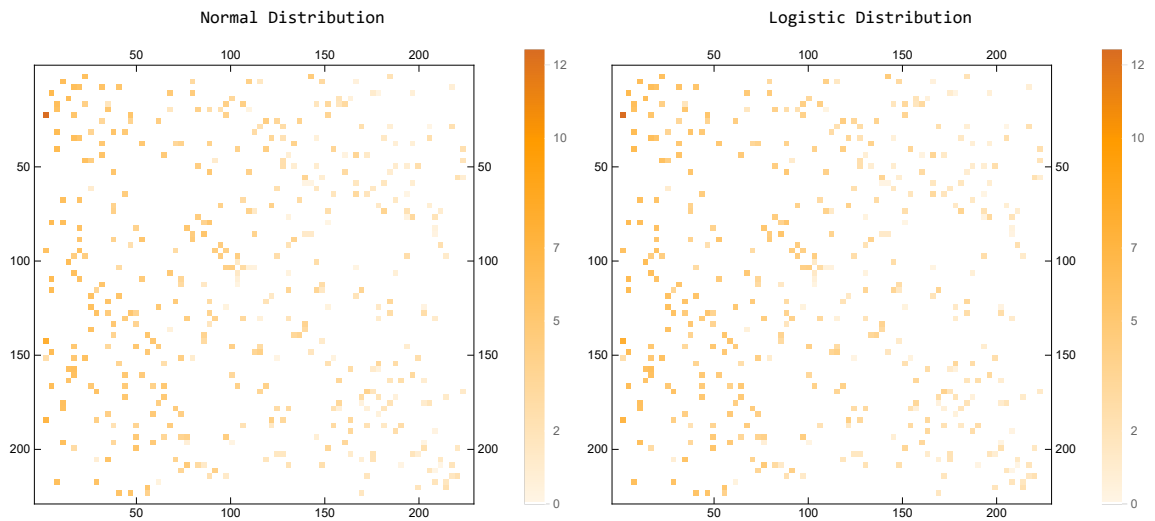


FIGURE 24. Distributed order communicability matrix of *NACE* sector 9605 with respect to Normal and Logistic distributions with order  $\alpha = 0.5$

## 4 Discussion and conclusion

For decision makers and policy makers working on occupational health and safety, how to improve workers' safety behavior is a focus. Analyzing the categorical data of workers who had an occupational accident by using effective mathematical methods other than conventional statistical methods yields very effective results. In this study, we present a novel mathematical method for the study of different sectors selected a significant sample of data in work-related accidents occurred in Turkey between the years 2013-2014 were used.

In order to obtain the network structure of workers who had an occupational accident using a categorical data set, firstly the data were parameterized. The hyper-network model, where each parameter corresponds to a hyper-edge, is established with a data set of 18 different sectors. Topological characterization of the created hyper-networks can be observed in hyper-edge degree distributions. The resulting hyper-edge degree distributions are quite similar to each other. The most striking differentiation in terms of hyper-edge degree distributions was observed to be the "Removal Sector" with 4942 *NACE* code. When the data of this sector are examined, it is seen that it differs from the data of other sectors analyzed in the study as an occupational accident characteristic. Hypergraphs have several simple graph embeddings. The first embedding we use in this study is the bipartite graph showing the vertices where the hyper-edges match. When we look at the peak order distributions in the  $G_B$  bipartite representations of  $H = (V, E)$  hyper-graphs created by different *NACE* sectors, it is observed that the frequency of the peaks in communication with each other is high. This density indicates that the  $G_C$  graphs encoding the communication characterization of the vertices are complete graphs. Thus, the hypothesis that there are short links between the occupational accident information of workers working in a sector is realized.

One of the main contribution of this paper is to present a new link-prediction method based on distributed order fractional derivatives. Distributed order derivatives are fractional derivatives that have been integrated over the order of the derivative within a given range; that is, the memory of agents in a system is distributed. As explained before, the institutional regulations can be considered to be power-law fading memory within a social environment. Hence, as we are predicting link formation in *MST* filtration of  $G_C$  embedding, we assume that evolution of a random walker on *MST* is expressed with a type of fractional matrix equation. Furthermore, we give such memory to random walker to be distributed on *MST*, then we express such evolution as distributed order fractional matrix equation. Such distributions are chosen to be normal and logistic distributions for numerical analysis. The solution of such equation is performed by finite difference scheme. Since *MST* is a discrete space for the evolution domain, finite difference scheme is performed respect to the size of vertex set of *MST*. In numerical computations, we choose fractional order derivative to be  $\alpha = 0.5$ . For further studies, such order can be chosen in arbitrary and even varying values to also study diffusion characteristics of random walker. The main goal of link prediction process is to determine absent links in a graph. The distributed order measure we present shows the most possible edges tend to be included in *MST*. As the new edges are included, *MST* will turn to be  $G_C$ . Numerical results show that the highest tendencies are in "Collection of non-hazardous waste" sector with 3811 *NACE* code, "Co operative store retail" sector with 4719 *NACE* code, and "Retail Sale Of Electrical Household Appliances, Furniture, Lighting Equipment And Other Household Articles In Specialized Stores." sector with 4759 *NACE* code for both normal and logistic distributions of the power-law fading kernel. Moreover, from Figures 5–24, it can be observed that the distribution of the power-law fading memory do not effect the link prediction values significantly.

Rather than the similar researches on social network analysis of occupational accidents, we analyze more than one sector. By introducing this new link prediction method based on distributed order fractional derivatives, this analyze can be performed on special sectors with bigger data for further studies.

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